

DESIGNING INTRAMEDULLAR POSTS FOR VETERINARY APPLICATIONS.

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Abstract: *The objective of this study is to describe the development of a low cost interlocking nail for young calves. Biomechanical parameters were measured for the numerical analysis of the bovine femoral repair system. Different polymeric and composite materials, polyacetal, polypropylene, polyamide and a glass fiber-reinforced polymer, were tested in silico to investigate their mechanical performance. Twelve femur models, divided into three groups, each one associated with a different fixation strategy, were used for simulation of an oblique simple fracture. Model loading conditions corresponded to a calf in transition (decubitus position to static position). The most critical stresses in the implant were found in the screws and at the interface between screw and nail. A numerical model demonstrated that all polymeric materials analyzed provided sufficient resistance to tolerate the loading imposed on the femur when an adequate fixation strategy was applied. After testing the biocompatibility of the material, in vivo tests will be conducted to validate the proposed design.*

1. Introduction

In cattle, fractures of long bones including femoral fractures are relatively frequent and great variety have been reported in the scientific literature [1- 4]. Diaphyseal femoral fractures in calves often occur following trauma during handling or a dystocia [2]. Several surgical techniques have been used in the stabilization of fractures of long bones: intramedullary pinning, cerclage wire, intramedullary interlocking nail fixation, rush pin fixation, bone plates and screws [1, 3]. The selection of treatment method depends on the

42 age of the animal, configuration of the fracture, and the surgeon's experience. Femoral
43 fractures usually require some form of internal fixation [1].
44 Despite recent developments, long bone fractures in large animals, especially diaphyseal
45 fractures, are still considered to be a challenge for veterinary surgeons, mainly due to
46 animal size and mass. In many cases, euthanasia is still considered as a choice to avoid
47 further financial loss and end suffering [4].
48 *Intramedullary interlocking nails (IIN)* have been used in human surgery to repair
49 fractures of the femur, humerus, and tibia. However, in veterinary orthopedics, the
50 available products that are used in surgery to fix bone fragments are too expensive and
51 are adapted from human devices [3]. Usually made with stainless steel, **IIN** may lead to
52 stress shielding.
53 There is a clinical demand for developing implants specifically designed to be used in
54 large animals. Several works have been developed by the biomechanics group of Federal
55 University of Minas Gerais to develop polymeric **IIN** for application in veterinary
56 orthopedics and to improve the surgical techniques applied in the repair of long bone
57 fractures.
58 In calves the **IIN** is an interesting option, as the thin cortical layer of the humerus does
59 not favor the application of orthopedic plaques, a usual treatment for these bones [5, 6].
60 In a previous work, the authors studied a system for internal immobilization of fractures
61 in long bones with the use of *polypropylene (PP)*, in the form of **IIN**. The reduction of
62 fractures in the diaphysis of the humerus of newborn calves by **IIN** proved to be feasible,
63 did not present complications in the postoperative period, allowed early use of the
64 operated limb [6].
65 Another study evaluated, *in vivo*, *polyacetal (POM)* and *polyamide (PA)* nails in the
66 form of **IIN** for immobilization of femoral fractures in young cattle. The nails did not
67 resist the stresses when the animals returned from the postoperative period and failed [7].
68 The response of bovine bone in the presence of an implant was investigated using Finite
69 Element Analysis (**FEA**) [8]; the remodelling results indicated that an **IIN** has the
70 advantage over the metallic one of improving long-term bone healing and possibly
71 avoiding the need of the implant removal.
72 **FEA** was used to model and estimate the performance of different polymers used in the
73 construction of **IIN**: **POM**, **PP** and **PA** [9]. The results demonstrated that none of the
74 polymers were sufficiently resistant to tolerate loading imposed on the femur during
75 walking and that the screws closer to the fracture line are critical stress areas.
76 Recently, polymer composites have emerged as biomaterials that could potentially
77 replace metallic alloys for use as orthopedic implants. Polyester resins in combinations
78 with reinforcements such as glass fiber offer chemical resistance and excellent
79 mechanical properties.
80 More recently three different polymers were used in the construction of **IIN**: **POM**, **PP**,
81 **PA** and *glass fiber-reinforced polymer (GFRP)*. Fixation strategies were improved
82 inspired in human orthopedic solutions, in an attempt to reduce stresses in critical regions
83 observed in previous experiments [7, 9].
84 According to ongoing studies on the biocompatibility, **GFRP** may be apply in the
85 manufacture of intramedullary nails for the treatment of fractures in calves (Rocha
86 Junior, personal communication).

87 This work has two objectives: (i) use **FEA** to test the hypothesis that a polymeric nail
88 (**GFRP, PP, PA** and **POM**) adapted for the characteristics of bovine anatomy may be
89 able to stabilize a femoral fracture in calves and (ii) investigate the effect of different
90 fixation strategies of the **IIN** on the mechanical behavior of a polymeric implant applied
91 for femoral fracture fixation in calves.

92

93 **2. Materials and methods**

94 *2.1. Sample*

95 Five Holstein male animals with a mean weight (\pm SD) of 62.8 ± 20.4 kgf (range 41.0-
96 85.0 kgf) and age 74 ± 15 days (range 60-90 days) were used in this study. All animals
97 were evaluated by a veterinarian and considered clinically healthy, with no history of
98 fractures. All procedures were evaluated and approved by the Ethical Commission on
99 Use of Animals (CEUA) of UFMG, Brazil.

100 *2.2. Data Collection*

101 First the animals were conducted in a straight line so that they would step on the force
102 plate (AMTI OR6-7 (©Advanced Mechanical Technology, Inc. USA)) with their right
103 pelvic member. The animals were then placed lying down, with the right pelvic limb
104 resting on the force plate and lifted while the measurement system acquired data on the
105 ground reaction force. Three force measurements were taken for each animal.
106 Contemphas (Contemphas, Germany) was used to synchronize force plate and video
107 capture system (Basler pi A640, Germany) set to a frequency of 100 Hz.

108 The pelvic limb of the animals was modeled by four rigid bodies interconnected by the
109 following joints: metatarsophalangeal, tibiotarsal, femorotibial and coxofemoral. These
110 joints were represented by anatomical landmarks similar to those defined in [10]. The
111 Simi-Motion 6.0 (Simi Reality Motion Systems, Germany) was used to digitize the
112 acquired videos and measure the four bony segments, Fig. 1.

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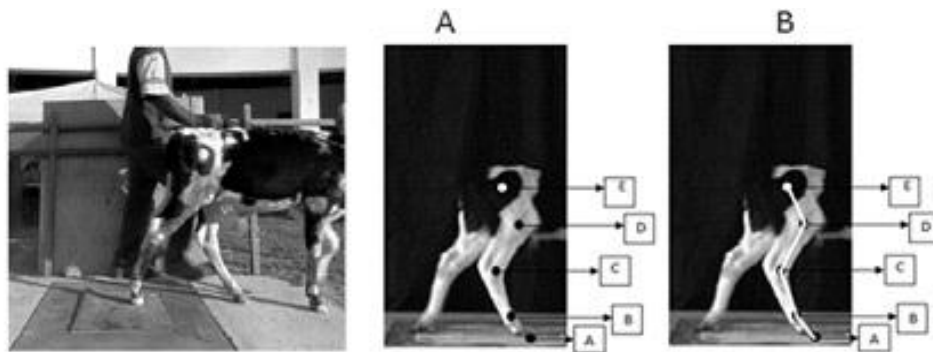
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123 Figure 1: A) Bony landmarks (A) ground contact point; (B) point representing
124 metatarsophalangeal joint; (C) point representing tibiotarsal joint; (D) point
125 representing femorotibial joint (E) point representing coxofemoral joint. B)
126 Bone segments : AB (hoof); BC (metatarsus); CD (tibia) e DE (femur).

127 Source: Author's database

128 *2.3. Femoral Joint Load Determination*

129

130 Coxofemoral joint loads were evaluated using static equilibrium and two-dimensional
131 inverse dynamics. The routines for two-dimensional inverse dynamics were developed
132 and implemented in MATLAB 2011. The input variables were body segment inertial
133 properties (**BSIP**) values determined according to a parametric method described in [11].
134 The forces acting on the joints of the right pelvic limbs of the calves were determined
135 when the ground reaction force (**GRF**) reached the peak in two conditions: during the
136 walking gait, and during the transition from the decubitus position on the platform to the
137 station position (**transition**). In the simulations, the forces during the **transition were**
138 **considered** since their components presented higher values when compared with the
139 values obtained during the walking gait. The muscle actions were not included as there
140 was no information available about the muscular action in the joints of calves during the
141 **transition**.

142 This research did not focus in the absolute values of stresses but in relative values. The
143 results obtained as each of the three blocking conditions (**BLK**) was qualitatively
144 compared to each other therefore the simplifications adopted in this research were quite
145 acceptable.

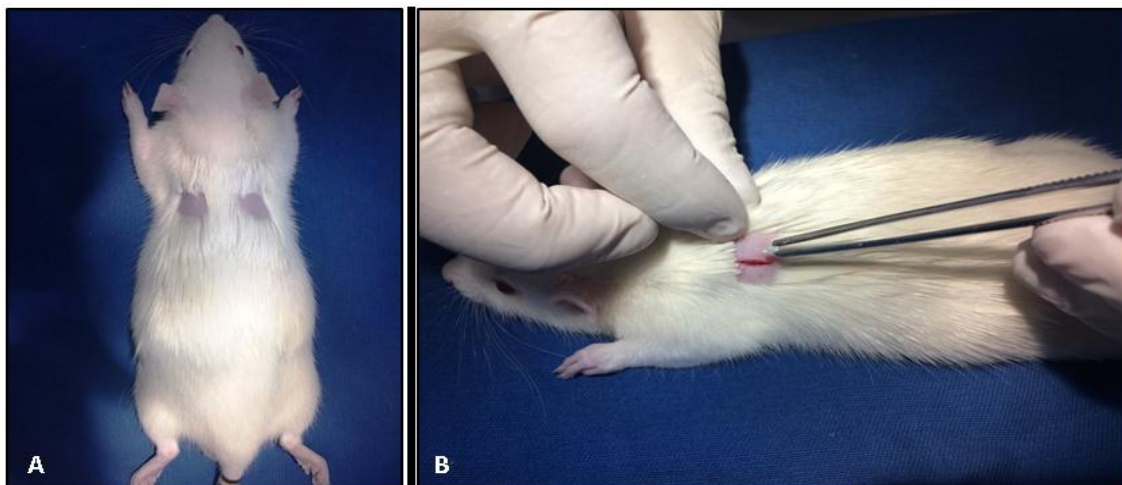
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147 *2.4 Analysis of biocompatibility*

148 The biocompatibility evaluation of GFRP, applied to build an IIN, was performed in
149 vivo. A fragment measuring about 0.5 cm² was implanted in the subcutaneous of healthy
150 rats after general anesthesia, Fig. 2. The implant remained in place for 45 days, where the
151 intimate region of the implanted device was submitted to microscopic evaluation [12]. A
152 commercial device similar to the test device was used as control.

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157 Figure 2: A) Tricotomy for insertion of fragments (right side - control), and GRPF (left side -
158 experimental). B) Insertion of the fragment into the subcutaneous tissue of the animal.

159 Source: Author's database.

160

161 2.5. Finite Element Modeling

162 To construct a femur geometric model two animals and two cadaveric specimens
163 underwent one CT session on axial tomography scanner Siemens, Somatom AR.T
164 (Siemens, Germany). The animals were examined under general intravenous anaesthesia
165 (xylazine (0.05 mg kg⁻¹), ketamine (2mg kg⁻¹) and midazolam (0.1mg kg⁻¹).

166 The obtained DICOM (© NEMA Arlington Virginia) format images allows a three-
167 dimensional reconstruction of the original anatomic structures, for this InVesalius 3.0
168 was used. This software allows separation of different tissues, bone and soft tissue
169 (muscles and fat) by use of coloured masques (segmentation).

170 The masques were exported as a triangular mesh, in stl format, for refinement using
171 Meshlab 1.3.3 (Istituto di Scienza e Tecnologie dell' Informazione, Italy). Then
172 Meshlab meshes were exported to SolidWorks 2012 (Dassault Systèmes, , France).

173 A femur geometric model was obtained in SolidWorks and exported to Abaqus (Dassault
174 Systèmes, France) and twelve finite element models were developed to simulate an
175 oblique simple fracture (40°, grade A2 by the AO/ASIF score system).

176 The models were divided into three groups, with each group associated with a specific
177 nail fixation strategy, referred as blocking condition (**BLK**) (Fig. 3).

178 Three **BLK** were used to block the **IIN**. The first **BLK** according previous study [8], two
179 other blocking situations, suggested in a DePuy Synthes surgical technique manual,
180 available for consultation at <http://osteosyntese.dk/wp-content/uploads/2014/11/>, noted
181 as suitable for use in distal femur fractures human, were also studied.
182



183

184 **Figure 3:** A) 1st condition (**BLK1**) four lateromedial direction cortical screws. B) 2nd
185 condition (**BLK2**) four lateromedial direction cortical screws, two at
186 proximal diaphysis and two at distal condylar region. C) 3rd condition
187 (**BLK3**) two lateromedial direction at distal condylar region and two
188 caudocranial direction at proximal diaphysis.
189

190 The nails were blocked by four 4.5 mm stainless steel cortical screws, inserted
191 perpendicular to the bone longitudinal axis. In **BLK1** the 1st screw was located 10 mm
192 from the fracture line, and the 2nd was 10 mm from the 1st screw (Fig. 3 – A). In the
193 **BLK2** and **BLK3** blocking conditions (Fig. 3 – B and Fig. 3 - C), at proximal diaphysis,
194 the 1st screw was located 20 mm from the fracture line, and the 2nd was located 10 mm

195 from the 1st screw. In the condylar region, the 1st screw was inserted below 10 mm of the
196 epiphyseal line and the 2nd 10 mm from the 1st, adapted from [13].

197 The femoral head had its translation movements restricted. Only translations in the
198 direction of an axis connecting the head to the center of the femorotibial joint were
199 allowed. The most lateral point of the distal epicondyle had its translational movements,
200 in the direction of the anteroposterior axis, restricted. The point considered as the center
201 of the femorotibial joint had all its translational degrees of freedom restricted [14].

202 Contact interactions among the different materials were established by considering tie
203 constraints, bone and nail bonded to the screws, as described in previous numerical
204 studies [9]. No contact was considered between bone surface and nail, and contact
205 between bones fragments was assumed to be frictionless.

206 Materials were modeled as homogeneous, isotropic and linear elastic. The mechanical
207 constants used for the **GFRP** material were calculated from the Halpin-Tsai equations
208 (Jones, 1999) and for **POM**, **PA** and **PP** were obtained from Black and Hastings (1998).

209 Mesh convergence analysis was performed until the error in maximum hip displacement
210 and strain energy was reduced to 3% [14]. The load was applied as a concentrated force
211 on the point of the femoral head in the direction of the axis formed by the center of the
212 hip joint and a point chosen to represent the tibiofemoral joint and a moment in the
213 proximal epicondyle region.

214 The maximum von Mises stresses were recorded for the screws and **IIN**, and the
215 maximum principal stress was recorded for the bone. All values were compared to the
216 yield and rupture points one of the four investigated materials, values above the yield
217 point or rupture stresses were considered to be indicative of failure.

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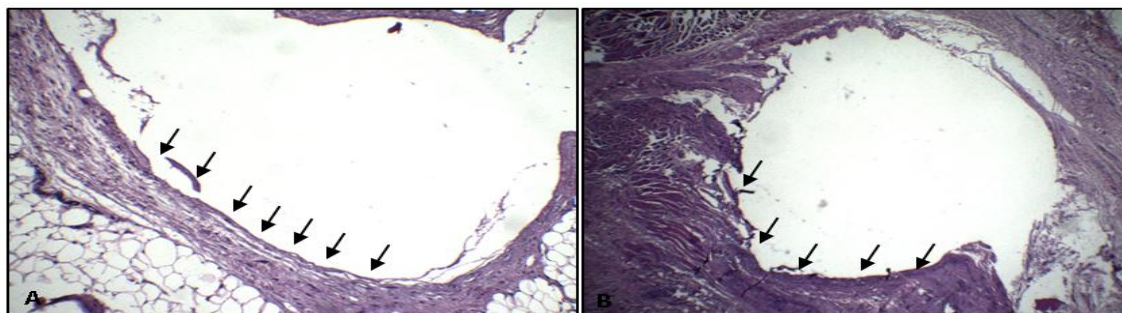
219 3. Results

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221 3.1 Histopathological Diagnosis

222 After the histopathological tests performed according to ISO 10993-6: Biological
223 evaluation of medical devices, Part 6: Tests for local effects after implantation (2007), the
224 **GFRP** were considered as moderately reactive. The semi-quantitative evaluation (based
225 on Hematoxylin and Eosin (**HE**) staining) presented score 5.0, thus becoming fit for use
226 in vivo. Among the findings there was the formation of a neovascularization around the
227 fragments, in addition, the formation of a fibrous capsule (Fig. 4).

228



229

230 **Figure 4:** Photomicrography, HE staining, 4x magnification. Arrows indicate the
231 formation of a fibrous capsule in the control group (4-A). Photomicrography
232 experimental group findings similar to the control group (4-B).

233 3.1 Simulations

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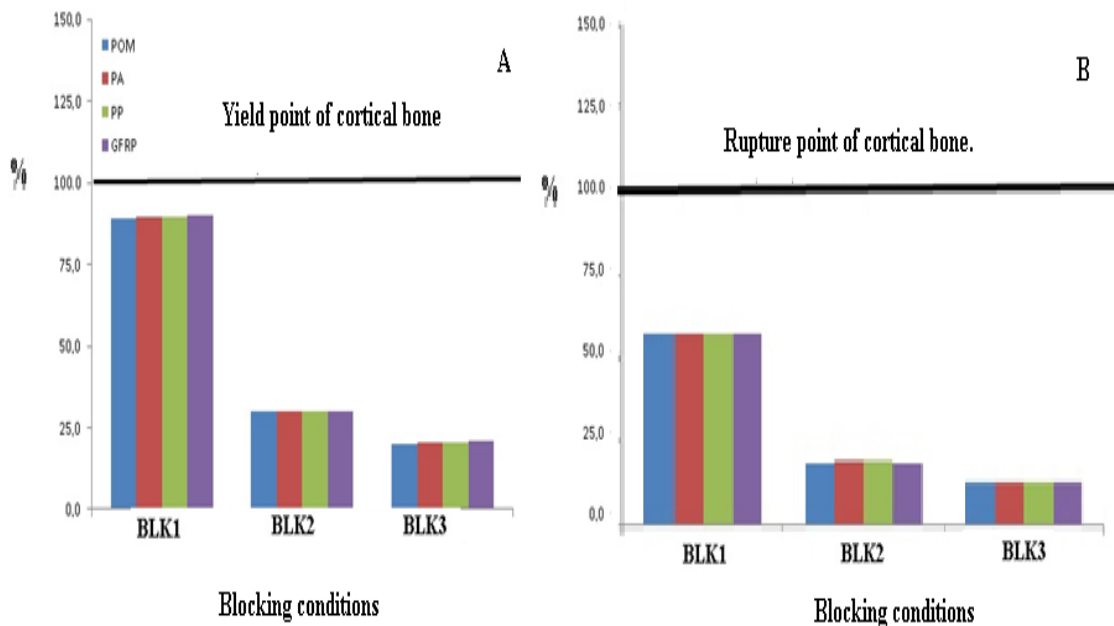
235 The screws and holes were numbered beginning at the most distal (1st screw) and
236 proceeding to the most proximal (4th screw).

237 The **BLK1**, **BLK2**, and **BLK3** showed bone mean stress (\pm SD) of 89.53 ± 0.30 (range
238 $89.30-90.04$ MPa), 29.96 ± 0.04 (range $29.93-30.02$ MPa), and 20.34 ± 0.22 (range
239 $20.19-20.72$ MPa) respectively.

240 The maximum principal stress values at the bone were always below yield and rupture
241 points. The magnitude of stress with **BLK1** was higher than those presented with the
242 other alternatives, regardless of the considered material (Fig. 5).

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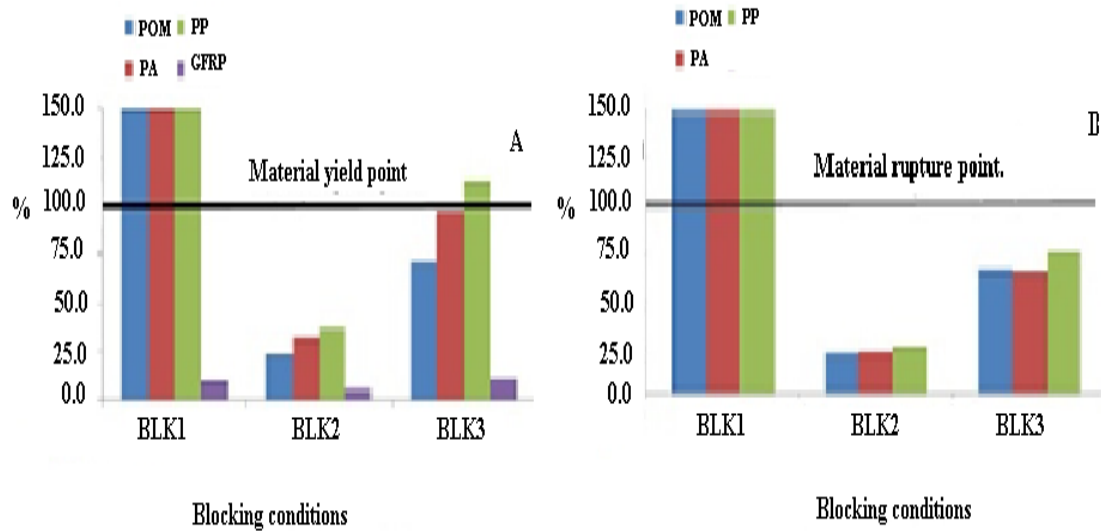
246 **Figure 5:** Percentages of maximum principal stresses in bones with different polymeric
247 interlocking nails relative to the bone yield point (A) and relative to the
248 bone compressive rupture point (B) when the bones were subjected to a load
249 in a model of bovine femoral fracture.

250

251

252 The simulations showed that equivalent stresses on the nail in some cases exceeded the
253 rupture point of the material. For **BLK1**, **POM**, **PA** and **PP** nails ruptured. Only the
254 **GFRP** nail did not fail for **BLK1**. The **PP** nail also failed in the **BLK3**, and the
255 equivalent stress values on the **PA** nail almost reached the yielding point of the material.
256 The values for the **GFRP** nail were not included in part B of the graph as the reference
257 rupture value for the material was not found (Fig. 6).

258



259
 260 **Figure 6:** Percentage of maximum von Mises stress in different polymeric interlocking
 261 nails relative to the material yield point (A) and the compressive rupture point
 262 (B) when the bones were subjected to a load in a model of bovine femoral
 263 fracture.
 264

265 For all materials, the maximum stress values at the bone model were found at the
 266 interface between the 1st screw and the screw hole for **BLK1** or **BLK2**. For **BLK3**, the
 267 maximum stress at the bone model occurred at the interface between the 4th screw and the
 268 screw hole. The maximum stress values at the nail for **BLK2** and **BLK3** were always
 269 found at the interface between the 1st screw and the screw hole. For **BLK1**, the stress
 270 values were dependent on the nail material. When **POM** and **PA** were used, the
 271 maximum values were found at the interface between the 1st screw and the screw hole.
 272 However, with the **PP** and **GFRP** nails, the maximum values occurred between the 3rd
 273 screw and the screw hole.
 274 All values for the equivalent stresses in the screws were below the yield stress of stainless
 275 steel (205 MPa). The stresses in screws for BLK2 were always lower than stresses for
 276 BLK1 and BLK3 when the screws closer to the fracture line (2nd and 3rd) were analyzed
 277 (Tab. 1).
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		Stress (MPa)					285
Material	Blocking condition	Bone (hole)	Nail (hole)	Screw			286
				1 st	2 nd	3 rd	4 th
POM	1 st	89.30 (1)	154.20(1)	179.20	146.10	166.70	171.00
	2 nd	29.93(1)	15.20(1)	29.98	18.43	22.24	107.4
	3 rd	20.19(4)	46.28(1)	30.31	73.18	175.70	114.40
PA	1 st	89.36(1)	130.20(1)	179.60	146.20	166.90	171.20
	2 nd	29.97(1)	13.07(1)	26.69	15.85	22.27	103.10
	3 rd	20.22(4)	38.88(1)	25.01	59.88	176.00	114.70
PP	1 st	89.42(1)	103.70(3)	180.20	146.50	195.80	171.40
	2 nd	30.02(1)	7.56(1)	21.56	14.86	22.32	103.40
	3 rd	20.23(4)	22.80(1)	17.43	44.30	176.50	115.90
GFRP	1 st	90.04(1)	90.75(3)	176.00	146.50	167.50	171.00
	2 nd	29.92(1)	54.69(1)	23.93	18.87	21.94	101.30
	3 rd	20.72(4)	102.80(1)	66.20	128.90	174.30	114.80

299 **Table 1:** Stress values for nails and screws (von Mises) and bone (maximum principal)

300

301 4. Discussion

302

303 In the simulations, the maximum stresses in the bone were found at the interface between
304 screws and the screw holes, where the load transfer was the greatest. The current results
305 showed that for the same **BLK**, the tensions in the bone model were quite similar for all
306 polymeric materials. This finding is in agreement with the previous study [9] and
307 suggests that bone tensions are dependent not only on the material used to build **IIN** but
308 also on the strategy used to stabilize the fracture.

309 The simulations showed higher stresses at the interface between screw and hole nails.
310 Interlocking screws placed proximal and distal to the fracture site restricted the
311 translation and rotation at the fracture site, which is important in oblique fractures that
312 rely on the screws for stability. However, the closer the distal screw was to the fracture,
313 the less cortical contact the nail had, which led to increased stresses on the screws,
314 putatively causes implant failure. This may explain why the polymeric nails failed in the
315 presence of the bending forces generated in the **transition** [7].

316 Simulations with **BLK1** did not provide the necessary implant stability, and failures
317 occurred in all polymeric nails except for the **GFRP** nail. Our results are in agreement
318 with an *in vivo* study [6], in which all polymeric nails that were used in conditions similar
319 to **BLK1** failed to fix femoral fractures in calves that were allowed to walk freely during
320 the early postoperative period.

321 The use of the **BLK2** resulted in a reduction in the stress values on all screws. The
322 stresses on the nails decreased approximately 58%, whereas the stress on the bone
323 increased approximately 47% compared with the value for the **BLK3**.

324 This suggest that polymeric nails are less resistant to bending when **BLK3** is applied,
325 thus increasing the contact area during loading, leading to an increase in the portion of
326 loads carried by the bone. This finding agrees with previous studies that found increased
327 loading levels on the bone when less stiff materials were used to manufacture
328 intramedullary nails [15].

329 The **GFRP** nail was resistant to forces and moments applied to the femur model. The
330 longitudinal glass fiber used to reinforce the composite nail may be responsible for
331 increasing the nail rigidity, but this possibility cannot be confirmed without experimental
332 validation.

333 In the simulations all of the materials used were resistant to deformation and rupture
334 when the **BLK2** was used. When **BLK3** was used the **PP** nail failed, and the von Mises
335 stress values on the **PA** nail almost reached the yield point of the material.

336 In the current study, the largest stress was found at the most distal nail hole. These
337 simulations results are similar with a previous study with similar blocking conditions that
338 found the largest equivalent von Mises stress at the same screw [15].

339

340 **5 Conclusions**

341

342 The early postoperative period is the most critical for the locking nail system since the
343 load is entirely transferred through the nail and the blocking screws without any load
344 sharing with the bone [16].

345 Several factors influence the performance of intramedullary nails in the fixation of
346 fractures of long bones, such as the femur design, nail material, nail length, number and
347 orientation of blocking screws, and distance from the blocking screws to fracture site
348 [17].

349 The **FEA** indicates that all polymeric materials (**POM**, **PA**, **PP** and **GFRP**) provided
350 sufficient resistance to tolerate the loading forces imposed on the femur during the
351 transition when an adequate blocking strategy was applied.

352

353 **6. Acknowledgment**

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356

357 **7. Disclosure Statement**

358 The authors declare that they have no competing interests.

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